

# **Fundamentals of Artificial Intelligence and Knowledge Representation (Module 2)**

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# 1 Propositional and first order logic

See Languages and Algorithms for AI (module 2).

## 2 Ontologies

<b>Ontology</b>	Formal (non-ambiguous) and explicit (obtainable through a finite sound procedure) description of a domain.	Ontology
<b>Category</b>	Can be organized hierarchically on different levels of generality.	Category
<b>Object</b>	Belongs to one or more categories.	Object
<b>Upper/general ontology</b>	Ontology focused on the most general domain.	Upper/general ontology
Properties:		
<ul style="list-style-type: none"><li>• Should be applicable to almost any special domain.</li><li>• Combining general concepts should not incur in inconsistencies.</li></ul>		
Approaches to create ontologies:		
<ul style="list-style-type: none"><li>• Created by philosophers/logicians/researchers.</li><li>• Automatic knowledge extraction from well-structured databases.</li><li>• Created from text documents (e.g. web).</li><li>• Crowd-sharing information.</li></ul>		

### 2.1 Categories

<b>Category</b>	Used in human reasoning when the goal is category-driven (in contrast to specific-instance-driven).	Category
In first order logic, categories can be represented through:		
<b>Predicate</b>	A predicate to tell if an object belongs to a category (e.g. <code>Car(c1)</code> indicates that <code>c1</code> is a car).	Predicate categories
<b>Reification</b>	Represent categories as objects as well (e.g. <code>c1 ∈ Car</code> ).	Reification

#### 2.1.1 Reification properties and operations

<b>Membership</b>	Indicates if an object belongs to a category. (e.g. <code>c1 ∈ Car</code> ).	Membership
<b>Subclass</b>	Indicates if a category is a subcategory of another one. (e.g. <code>Car ⊂ Vehicle</code> ).	Subclass
<b>Necessity</b>	Members of a category enjoy some properties (e.g. $(x \in \text{Car}) \Rightarrow \text{hasWheels}(x)$ ).	Necessity
<b>Sufficiency</b>	Sufficient conditions to be part of a category (e.g. $\text{hasPlate}(x) \wedge \text{hasWheels}(x) \Rightarrow x \in \text{Car}$ ).	Sufficiency
<b>Category-level properties</b>	Category themselves can enjoy properties (e.g. <code>Car ∈ VehicleType</code> )	Category-level properties

<b>Disjointness</b>	Given a set of categories $S$ , the categories in $S$ are disjoint iff they all have different objects:	Disjointness
	$\text{disjoint}(S) \iff (\forall c_1, c_2 \in S, c_1 \neq c_2 \Rightarrow c_1 \cap c_2 = \emptyset)$	
<b>Exhaustive decomposition</b>	Given a category $c$ and a set of categories $S$ , $S$ is an exhaustive decomposition of $c$ iff any element in $c$ belongs to at least a category in $S$ :	Exhaustive decomposition
	$\text{exhaustiveDecomposition}(S, c) \iff (\forall o \in c \iff \exists c_2 \in S : o \in c_2)$	
<b>Partition</b>	Given a category $c$ and a set of categories $S$ , $S$ is a partition of $c$ when:	Partition
	$\text{partition}(S, c) \iff \text{disjoint}(S) \wedge \text{exhaustiveDecomposition}(S, c)$	
<b>2.1.2 Physical composition</b>		
	Objects (meronyms) are part of a whole (holonym).	
<b>Part-of</b>	If the objects have a structural relation (e.g. <code>partOf(cylinder1, engine1)</code> ). Properties:	Part-of
	<b>Transitivity</b> $\text{partOf}(x, y) \wedge \text{partOf}(y, z) \Rightarrow \text{partOf}(x, z)$ <b>Reflexivity</b> $\text{partOf}(x, x)$	
<b>Bunch-of</b>	If the objects do not have a structural relation. Useful to define a composition of countable objects (e.g. <code>bunchOf(nail1, nail3, nail4)</code> ).	Bunch-of
<b>2.1.3 Measures</b>		
	A property of objects.	
<b>Quantitative measure</b>	Something that can be measured using a unit (e.g. <code>length(table1) = cm(80)</code> ). Qualitative measures propagate when using <code>partOf</code> or <code>bunchOf</code> (e.g. the weight of a car is the sum of its parts).	Quantitative measure
<b>Qualitative measure</b>	Something that can be measured using terms with a partial or total order relation (e.g. <code>{good, neutral, bad}</code> ). Qualitative measures do not propagate when using <code>partOf</code> or <code>bunchOf</code> .	Qualitative measure
<b>Fuzzy logic</b>	Provides a semantics to qualitative measures (i.e. convert qualitative to quantitative).	Fuzzy logic
<b>2.1.4 Things vs stuff</b>		
<b>Intrinsic property</b>	Related to the substance of the object. It is retained when the object is divided (e.g. water boils at 100°C).	Intrinsic property
<b>Extrinsic property</b>	Related to the structure of the object. It is not retained when the object is divided (e.g. the weight of an object changes when split).	Extrinsic property
<b>Substance</b>	Category of objects with only intrinsic properties.	Substance
<b>Stuff</b>	The most general substance category.	Stuff
<b>Count noun</b>	Category of objects with only extrinsic properties.	Count noun
<b>Things</b>	The most general object category.	Things

## 2.2 Semantic networks

Graphical representation of objects and categories connected through labelled links.

Semantic networks

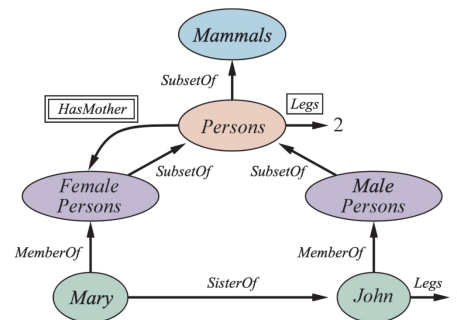


Figure 2.1: Example of semantic network

**Objects and categories** Represented using the same symbol.

**Links** Four different types of links:

- Relation between objects (e.g. **SisterOf**).
- Property of a category (e.g. **2 Legs**).
- Is-a relation (e.g. **SubsetOf**).
- Property of the members of a category (e.g. **HasMother**).

**Single inheritance reasoning** Starting from an object, check if it has the queried property. If not, iteratively move up to the category it belongs to and check for the property.

Single inheritance reasoning

**Multiple inheritance reasoning** Reasoning is not possible as it is not clear which parent to choose.

Multiple inheritance reasoning

**Limitations** Compared to first order logic, semantic networks do not have:

- Negations.
- Universally and existentially quantified properties.
- Disjunctions.
- Nested function symbols.

Many semantic network systems allow to attach special procedures to handle special cases that the standard inference algorithm cannot handle. This approach is powerful but does not have a corresponding logical meaning.

**Advantages** With semantic networks it is easy to attach default properties to categories and override them on the objects (i.e. **Legs** of **John**).

## 2.3 Frames

Knowledge that describes an object in terms of its properties. Each frame has:

Frames

- An unique name
- Properties represented as pairs `<slot - filler>`

### Example.

```
(  
  toronto  
    <:Instance-Of City>  
    <:Province ontario>  
    <:Population 4.5M>  
)
```

**Prototype** Members of a category used as comparison metric to determine if another object belongs to the same class (i.e. an object belongs to a category if it is similar enough to the prototypes of that category). Prototype

**Defeasible value** Value that is allowed to be different when comparing an object to a prototype. Defeasible value

**Facets** Additional information contained in a slot for its filler (e.g. default value, type, domain). Facets

**Procedural information** Fillers can be a procedure that can be activated by specific facets:

if-needed Looks for the value of the slot.

if-added Adds a value.

if-removed Removes a value.

### Example.

```
(  
  toronto  
    <:Instance-Of City>  
    <:Province ontario>  
    <:Population [if-needed QueryDB]>  
)
```

## 3 Description logic

### 3.1 Syntax

**Logical symbols** Symbols with fixed meaning.

Logical symbols

**Punctuation** ( ) [ ]

**Positive integers**

**Concept-forming operators** ALL, EXISTS, FILLS, AND

**Connectives**  $\sqsubseteq$ ,  $\doteq$ ,  $\rightarrow$

**Non-logical symbols** Domain-dependant symbols.

Non-logical symbols

**Atomic concepts** Categories (CamelCase, e.g. Person).

**Roles** Used to describe objects (:CamelCase, e.g. :Height).

**Constants** (camelCase, e.g. johnDoe).

**Complex concept** Concept-forming operators can be used to combine atomic concepts and form complex concepts. A well-formed concept follows the conditions:

Complex concept

- An atomic concept is a concept.
- If  $r$  is a role and  $d$  is a concept, then  $[ALL\ r\ d]$  is a concept.
- If  $r$  is a role and  $n$  is a positive integer, then  $[EXISTS\ n\ r]$  is a concept.
- If  $r$  is a role and  $c$  is a constant, then  $[FILLS\ r\ c]$  is a concept.
- If  $d_1 \dots d_n$  are concepts, then  $[AND\ d_1 \dots d_n]$  is a concept.

**Sentence** Connectives can be used to combine concepts and form sentences. A well-formed sentence follows the conditions:

Sentence

- If  $d_1$  and  $d_2$  are concepts, then  $(d_1 \sqsubseteq d_2)$  is a sentence.
- If  $d_1$  and  $d_2$  are concepts, then  $(d_1 \doteq d_2)$  is a sentence.
- If  $c$  is a constant and  $d$  is a concept, then  $(c \rightarrow d)$  is a sentence.

**Knowledge base** Collection of sentences.

Knowledge base

**Constants** are individuals of the domain.

**Concepts** are categories of individuals.

**Roles** are binary relations between individuals.

**Assertion box (A-box)** List of facts about individuals.

Assertion box  
(A-box)

**Terminological box (T-box)** List of sentences (axioms) about concepts.

Terminological box  
(T-box)



## 3.2 Semantics

### 3.2.1 Concept-forming operators

Let  $r$  be a role,  $d$  be a concept,  $c$  be a constant and  $n$  a positive integer. The semantics of concept-forming operators are:

Concept-forming operators

$[ALL \ r \ d]$  Individuals  $r$ -related to the individuals of the category  $d$ .

**Example.**  $[ALL \ :HasChild \ Male]$  individuals that have zero children or only male children.

$[EXISTS \ n \ r]$  Individuals  $r$ -related to at least  $n$  other individuals.

**Example.**  $[EXISTS \ 1 \ :Child]$  individuals with at least one child.

$[FILLS \ r \ c]$  Individuals  $r$ -related to the individual  $c$ .

**Example.**  $[FILLS \ :Child \ john]$  individuals with child john.

$[AND \ d_1 \dots d_n]$  Individuals belonging to all the categories  $d_1 \dots d_n$ .

### 3.2.2 Sentences

Sentences are expressions with truth values in the domain. Let  $d$  be a concept and  $c$  be a constant. The semantics of sentences are:

Sentences

$d_1 \sqsubseteq d_2$  Concept  $d_1$  is subsumed by  $d_2$ .

**Example.**  $PhDStudent \sqsubseteq Student$  as every PhD is also a student.

$d_1 \doteq d_2$  Concept  $d_1$  is equivalent to  $d_2$ .

**Example.**  $PhDStudent \doteq [AND \ Student \ :Graduated \ :HasFunding]$

$c \rightarrow d$  The individual  $c$  satisfies the description of the concept  $d$ .

**Example.**  $federico \rightarrow Professor$

### 3.2.3 Interpretation

**Interpretation** An interpretation  $\mathcal{I}$  in description logic is a pair  $(\mathcal{D}, \mathcal{I})$  where:

Interpretation

- $\mathcal{D}$  is the domain.
- $\mathcal{I}$  is the interpretation mapping.

**Constant** Let  $c$  be a constant,  $\mathcal{I}[c] \in \mathcal{D}$ .

**Atomic concept** Let  $a$  be an atomic concept,  $\mathcal{I}[a] \subseteq \mathcal{D}$ .

**Role** Let  $r$  be a role,  $\mathcal{I}[r] \subseteq \mathcal{D} \times \mathcal{D}$ .

**Thing** The concept **Thing** corresponds to the domain:  $\mathcal{I}[\mathbf{Thing}] = \mathcal{D}$ .

$[ALL \ r \ d]$

$$\mathcal{I}[[ALL \ r \ d]] = \{x \in \mathcal{D} \mid \forall y : \langle x, y \rangle \in \mathcal{I}[r] \text{ then } y \in \mathcal{I}[d]\}$$

$[EXISTS \ n \ r]$

$$\mathcal{I}[[EXISTS \ n \ r]] = \{x \in \mathcal{D} \mid \text{exists at least } n \text{ distinct } y : \langle x, y \rangle \in \mathcal{I}[r]\}$$

[FILLS  $r \ c$ ]

$$\mathcal{I}[\text{[FILLS } r \ c]] = \{x \in \mathcal{D} \mid \langle x, \mathcal{I}[c] \rangle \in \mathcal{I}[r]\}$$

[AND  $d_1 \dots d_n$ ]

$$\mathcal{I}[\text{[AND } d_1 \dots d_n]] = \mathcal{I}[d_1] \cap \dots \cap \mathcal{I}[d_n]$$

**Model** Given an interpretation  $\mathcal{J} = (\mathcal{D}, \mathcal{I})$ , a sentence is true under  $\mathcal{J}$  ( $\mathcal{J} \models \text{sentence}$ ) if:

Model

- $\mathcal{J} \models (c \rightarrow d)$  iff  $\mathcal{I}[c] \in \mathcal{I}[d]$ .
- $\mathcal{J} \models (d_1 \sqsubseteq d_2)$  iff  $\mathcal{I}[d_1] \subseteq \mathcal{I}[d_2]$ .
- $\mathcal{J} \models (d_1 \doteq d_2)$  iff  $\mathcal{I}[d_1] = \mathcal{I}[d_2]$ .

Given a set of sentences  $S$ ,  $\mathcal{J}$  models  $S$  if  $\mathcal{J} \models S$ .

**Entailment** A set of sentences  $S$  logically entails a sentence  $\alpha$  if:

Entailment

$$\forall \mathcal{J} : (\mathcal{J} \models S) \rightarrow (\mathcal{J} \models \alpha)$$

## 3.3 Reasoning

### 3.3.1 T-box reasoning

Given a knowledge base of a set of sentences  $S$ , we would like to be able to determine the following:

**Satisfiability** A concept  $d$  is satisfiable w.r.t.  $S$  if:

Satisfiability

$$\exists \mathcal{J}, (\mathcal{J} \models S) : \mathcal{J}[d] \neq \emptyset$$

**Subsumption** A concept  $d_1$  is subsumed by  $d_2$  w.r.t.  $S$  if:

Subsumption

$$\forall \mathcal{J}, (\mathcal{J} \models S) : \mathcal{J}[d_1] \subseteq \mathcal{J}[d_2]$$

**Equivalence** A concept  $d_1$  is equivalent to  $d_2$  w.r.t.  $S$  if:

Equivalence

$$\forall \mathcal{J}, (\mathcal{J} \models S) : \mathcal{J}[d_1] = \mathcal{J}[d_2]$$

**Disjointness** A concept  $d_1$  is disjoint to  $d_2$  w.r.t.  $S$  if:

Disjointness

$$\forall \mathcal{J}, (\mathcal{J} \models S) : \mathcal{J}[d_1] \cap \mathcal{J}[d_2] = \emptyset$$

**Theorem 3.3.1** (Reduction to subsumption). Given the concepts  $d_1$  and  $d_2$ , it holds that:

Reduction to subsumption

- $d_1$  is unsatisfiable  $\iff d_1 \sqsubseteq \perp$ .
- $d_1 \doteq d_2 \iff d_1 \sqsubseteq d_2 \wedge d_2 \sqsubseteq d_1$ .
- $d_1$  and  $d_2$  are disjoint  $\iff (d_1 \sqcap d_2) \sqsubseteq \perp$ .

### 3.3.2 A-box reasoning

Given a constant  $c$ , a concept  $d$  and a set of sentences  $S$ , we can determine the following:

**Satisfiability** A constant  $c$  satisfies the concept  $d$  if:

Satisfiability

$$S \models (c \rightarrow d)$$

Note that it can be reduced to subsumption.

### 3.3.3 Computing subsumptions

Given a knowledge base  $KB$  and two concepts  $d$  and  $e$ , we want to prove:

$$KB \models (d \sqsubseteq e)$$

The following algorithms can be employed:

#### Structural matching

Structural matching

1. Normalize  $d$  and  $e$  into a conjunctive form:

$$d = [\text{AND } d_1 \dots d_n] \quad e = [\text{AND } e_1 \dots e_m]$$

2. Check if each part of  $e$  is accounted by at least a component of  $d$ .

#### Tableaux-based algorithms

Exploit the following theorem:

Tableaux-based algorithms

$$(KB \models (C \sqsubseteq D)) \iff (KB \cup (x : C \sqcap \neg D)) \text{ is inconsistent}$$

Note: similar to refutation.

### 3.3.4 Open world assumption

**Open world assumption** If a sentence cannot be inferred, its truth values is unknown.

Open world assumption

Description logics are based on the open world assumption. To reason in open world assumption, all the possible models are split upon encountering an unknown facts depending on the possible cases (Oedipus example).

## 3.4 Expanding description logic

It is possible to expand a description logic by:

**Adding concept-forming operators** Let  $r$  be a role,  $d$  be a concept,  $c$  be a constant and  $n$  a positive integer. We can extend our description logic with:

Adding concept-forming operators

[AT-MOST  $n$   $r$ ] Individuals  $r$ -related to at most  $n$  other individuals.

**Example.** [AT-MOST 1 :Child] individuals with only a child.

[ONE-OF  $c_1 \dots c_n$ ] Concept only satisfied by  $c_1 \dots c_n$ .

**Example.** Beatles  $\doteq$  [ALL :BandMember [ONE-OF john paul george ringo]]

[EXISTS  $n$   $r$   $d$ ] Individuals  $r$ -related to at least  $n$  individuals in the category  $d$ .

**Example.** [EXISTS 2 :Child Male] individuals with at least two male children.

Note: this increases the computational complexity of entailment.

#### Relating roles

Relating roles

[SAME-AS  $r_1$   $r_2$ ] Equates fillers of the roles  $r_1$  and  $r_2$

**Example.** [SAME-AS :CEO :Owner]

Note: this increases the computational complexity of entailment. Role chaining also leads to undecidability.

**Adding rules** Rules are useful to add conditions (e.g. if  $d_1$  then [FILLS  $r$   $c$ ]).

Adding rules

### 3.5 Description logics family

Depending on the number of operators, a description logic can be:

- More expressive.
- Computationally more expensive.
- Undecidable.

**Attributive language ( $\mathcal{AL}$ )** Minimal description logic with:

- Atomic concepts.
- Universal concept (**Thing** or  $\top$ ).
- Bottom concept (**Nothing** or  $\perp$ ).
- Atomic negation (only for atomic concepts).
- AND operator ( $\sqcap$ ).
- ALL operator ( $\forall$ ).
- [EXISTS 1 r] operator ( $\exists$ ).

**Attributive language complement ( $\mathcal{ALC}$ )**  $\mathcal{AL}$  with negation for concepts.

$\mathcal{F}$	Functional properties
$\mathcal{E}$	Full existential quantification
$\mathcal{U}$	Concept union
$\mathcal{C}$	Complex concept negation
$\mathcal{S}$	$\mathcal{ALC}$ with transitive roles
$\mathcal{H}$	Role hierarchy
$\mathcal{R}$	Limited complex roles axioms Reflexivity and irreflexivity Roles disjointness
$\mathcal{O}$	Nominals
$\mathcal{I}$	Inverse properties
$\mathcal{N}$	Cardinality restrictions
$\mathcal{Q}$	Qualified cardinality restrictions
$(\mathcal{D})$	Datatype properties, data values and data types

Table 3.1: Name and expressivity of logics

## 4 Web reasoning

### 4.1 Semantic web

**Semantic web** Method to represent and reason on the data available on the web. Semantic web aims to preserve the characteristics of the web, this includes:

- Globality.
- Information distribution.
- Information inconsistency of contents and links (as everyone can publish).
- Information incompleteness of contents and links.

Information is structured using ontologies and logic is used as inference mechanism. New knowledge can be derived through proofs.

**Uniform resource identifier** Naming system to uniquely identify concepts. Each URI correspond to one and only one concept, but multiple URIs can refer to the same concept.

**XML** Markup language to represent hierarchically structured data. An XML can contain in its preamble the description of the grammar used within the document.

**Resource description framework (RDF)** XML-based language to represent knowledge. Based on triplets:

<subject, predicate, object>  
<resource, attribute, value>

RDF supports:

**Types** Using the attribute `type` which can assume an URI as value.

**Collections** Subjects and objects can be bags, sequences or alternatives.

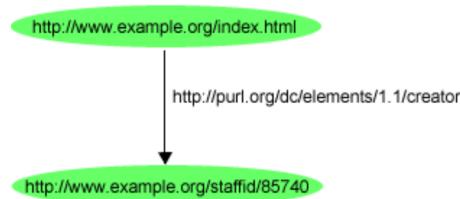
**Meta-sentences** Reification of the sentences (e.g. "X says that Y...").

**RDF schema** RDF can be used to describe classes and relations with other classes (e.g. `type`, `subClassOf`, `subPropertyOf`, ...)

#### Representation

**Graph** A graph where nodes are subjects or objects and edges are predicates.

**Example.**



The graph stands for: `http://www.example.org/index.html` has a creator with staff id 85740.

## XML

### Example.

```
<rdf:RDF
xmlns:rdf=http://www.w3.org/1999/02/22-rdf-syntax-ns#
xmlns:contact=http://www.w3.org/2000/10/swap/pim/contact#>
  <contact:Person rdf:about="http://www.w3.org/People/EM/
    contact#me">
    <contact:fullName>Eric Miller</contact:fullName>
    <contact:mailbox rdf:resource="mailto:em@w3.org"/>
    <contact:personalTitle>Dr.</contact:personalTitle>
  </contact:Person>
</rdf:RDF>
```

**Database similarities** RDF aims to integrate different databases:

- A DB record is a RDF node.
- The name of a column can be seen as a property type.
- The value of a field corresponds to the value of a property.

**RDFa** Specification to integrate XHTML and RDF.

RDFa

**SPARQL** Language to query different data sources that support RDF (natively or through a middleware).

SPARQL

**Ontology web language (OWL)** Ontology based on RDF and description logic fragments. Three level of expressivity are available:

Ontology web language (OWL)

- OWL lite.
- OWL DL.
- OWL full.

An OWL has:

**Classes** Categories.

**Properties** Roles and relations.

**Instances** Individuals.

## 4.2 Knowledge graphs

**Knowledge graph** Knowledge graphs overcome the computational complexity of T-box reasoning with semantic web and description logics.

Knowledge graph

- Use a simple vocabulary with a simple but robust corpus of types and properties adopted as a standard.
- Represent a graph with terms as nodes and edges connecting them. Knowledge is therefore represented as triplets (**h**, **r**, **t**) where **h** and **t** are entities and **r** is a relation.
- Logic formulas are removed. T-box and A-box can be seen as the same concept. There is no reasoning but only facts.

- Data does not have a conceptual schema and can come from different sources with different semantics.
- Graph algorithms to traverse the graph and solve queries.

#### KG quality

Quality

**Coverage** If the graph has all the required information.

**Correctness** If the information is correct (can be objective or subjective).

**Freshness** If the content is up-to-date.

**Graph embedding** Project entities and relations into a vectorial space for ML applications.

Graph embedding

**Entity prediction** Given two entities  $h$  and  $t$ , determine the relation  $r$  between them.

**Link prediction** Given an entity  $h$  and a relation  $t$ , determine an entity  $t$  related to  $h$ .

## 5 Quantitative time reasoning

### 5.1 Propositional logic

**State** The current state of the world can be represented as a set of propositions that are true according the observation of an agent. State

The union of a countable sequence of states represents the evolution of the world. Each proposition is distinguished by its time step.

**Example.** A child has a bow and an arrow, then shoots the arrow.

$$\begin{aligned} \text{KB}^0 &= \{\text{hasBow}^0, \text{hasArrow}^0\} \\ \text{KB}^1 &= \{\text{hasBow}^0, \text{hasArrow}^0, \text{hasBow}^1, \neg \text{hasArrow}^1\} \end{aligned}$$

**Action** An action indicates how a state evolves into the next one. It is described using effect axioms in the form: Action

$$\text{action}^t \Rightarrow (\text{preconditions}^t \iff \text{effects}^{t+1})$$

**Frame problem** The effect axioms of an action do not tell what remains unchanged in the next state. Frame problem

**Frame axioms** The frame axioms of an action describe the unaffected propositions of an action. Frame axioms

**Example.** The action of shooting an arrow can be described as:

$$\begin{aligned} \text{SHOOT}^t &\Rightarrow \{\text{hasArrow}^t \iff \neg \text{hasArrow}^{t+1}\} \\ \text{SHOOT}^t &\Rightarrow \{\text{hasBow}^t \iff \text{hasBow}^{t+1}\} \end{aligned}$$

Note that with  $m$  actions and  $n$  propositions, the number of frame axioms will be of order  $O(mn)$ . Inference for  $t$  time steps will have complexity  $O(nt)$ .

### 5.2 Situation calculus (Green's formulation)

Situation calculus uses first order logic instead of propositional logic.

**Situation** The initial state is a situation. Applying an action in a situation is a situation: Situation

$$s \text{ is a situation and } \mathbf{a} \text{ is an action} \iff \text{result}(\mathbf{a}, s) \text{ is situation}$$

(Note: in FAIRK module 1, **result** is denoted as **do**).

**Fluent** Function that varies depending on the situation (i.e. tells if a property holds in a given situation). Fluent

**Example.**  $\text{hasBow}(s)$  where  $s$  is a situation.



**Action** Actions are described using:

Action

**Possibility axioms** Indicates the preconditions  $\phi_a$  of an action  $a$  in a given situation  $s$ :

Possibility axioms

$$\phi_a(s) \Rightarrow \text{poss}(a, s)$$

**Successor state axiom** The evolution of a fluent  $F$  follows the axiom:

Successor state axiom

$$F^{t+1} \iff (\text{ActionCauses}(F) \vee (F^t \wedge \neg \text{ActionCauses}(\neg F)))$$

In other words, a fluent is true if an action makes it true or does not change if the action does not involve it.

Adding the notion of possibility, an action can be described as:

$$\begin{aligned} \text{poss}(a, s) \Rightarrow & \left( F(\text{result}(a, s)) \iff \right. \\ & (a = \text{ActionCauses}(F)) \vee \\ & \left. (F(s) \wedge a \neq \neg \text{ActionCauses}(\neg F)) \right) \end{aligned}$$

**Unique action axiom** Only a single action can be executed in a situation to avoid non-determinism.

Unique action axiom

## 5.3 Event calculus (Kowalski's formulation)

Event calculus reifies fluents and events (actions) as terms (instead of predicates).

**Event calculus ontology** A fixed set of predicates:

Event calculus ontology

$\text{holdsAt}(F, T)$  The fluent  $F$  holds at time  $T$ .

$\text{happens}(E, T)$  The event  $E$  (i.e. execution of an action) happened at time  $T$ .

$\text{initiates}(E, F, T)$  The event  $E$  causes the fluent  $F$  to start holding at time  $T$ .

$\text{terminates}(E, F, T)$  The event  $E$  causes the fluent  $F$  to cease holding at time  $T$ .

$\text{clipped}(T_i, F, T_j)$  The fluent  $F$  has been made false between the times  $T_i$  and  $T_j$  ( $T_i < T_j$ ).

$\text{initially}(F)$  The fluent  $F$  holds at time 0.

**Domain-independent axioms** A fixed set of axioms:

Domain-independent axioms

### Truthness of a fluent

1. A fluent holds if an event initiated it in the past and has not been clipped.

$$\begin{aligned} \text{holdsAt}(F, T_j) \Leftarrow & \text{happens}(E, T_i) \wedge (T_i < T_j) \wedge \\ & \text{initiates}(E, F, T_i) \wedge \neg \text{clipped}(T_i, F, T_j) \end{aligned}$$

2. A fluent holds if it was initially true and has not been clipped.

$$\text{holdsAt}(F, T) \Leftarrow \text{initially}(F) \wedge \neg \text{clipped}(0, F, T)$$

Note: the negations make the definition of these axioms in Prolog unsafe.

### Clipping of a fluent

$$\text{clipped}(T_i, F, T_j) \Leftarrow \text{happens}(E, T) \wedge (T_i < T < T_j) \wedge \text{terminates}(E, F, T)$$

**Domain-dependent axioms** Domain-specific axioms defined using the predicates `initially`, `initiates` and `terminates`.

Domain-dependent axioms

**Deductive reasoning** Event calculus only allows deductive reasoning: it takes as input the domain-dependant axioms and a set of events, and computes a set of true fluents. If a new event is observed, the query need to be recomputed again.

**Example.** A room with a light and a button can be described as:

**Fluents** `lightOn · lightOff`

**Events** `PUSH_BUTTON`

Domain-dependent axioms are:

**Initial state** `initially(lightOff)`

**Effects of PUSH\_BUTTON on lightOn**

- `initiates(PUSH_BUTTON, lightOn, T)  $\Leftarrow$  holdsAt(lightOff, T)`
- `terminates(PUSH_BUTTON, lightOn, T)  $\Leftarrow$  holdsAt(lightOn, T)`

**Effects of PUSH\_BUTTON on lightOff**

- `initiates(PUSH_BUTTON, lightOff, T)  $\Leftarrow$  holdsAt(lightOn, T)`
- `terminates(PUSH_BUTTON, lightOff, T)  $\Leftarrow$  holdsAt(lightOff, T)`

A set of events could be:

$$\text{happens}(\text{PUSH\_BUTTON}, 3) \cdot \text{happens}(\text{PUSH\_BUTTON}, 5) \cdot \text{happens}(\text{PUSH\_BUTTON}, 6)$$

### 5.3.1 Reactive event calculus

Allows to add events dynamically without the need to recompute the result.

Reactive event calculus

## 5.4 Allen's logic of intervals

Event calculus only captures instantaneous events that happen in given points in time.

**Allen's logic of intervals** Reasoning on time intervals.

Allen's logic of intervals  
Interval

**Interval** An interval  $i$  starts at a time `begin(i)` and ends at a time `end(i)`.

**Temporal operators**

Temporal operators

- `meet(i, j)  $\iff$  end(i) = begin(j)`
- `before(i, j)  $\iff$  end(i) < begin(j)`
- `after(i, j)  $\iff$  before(j, i)`
- `during(i, j)  $\iff$  begin(j) < begin(i) < end(i) < end(j)`
- `overlap(i, j)  $\iff$  begin(i) < begin(j) < end(i) < end(j)`

- $\text{starts}(i, j) \iff \text{begin}(i) = \text{begin}(j)$
- $\text{finishes}(i, j) \iff \text{end}(i) = \text{end}(j)$
- $\text{equals}(i, j) \iff \text{starts}(i, j) \wedge \text{ends}(i, j)$

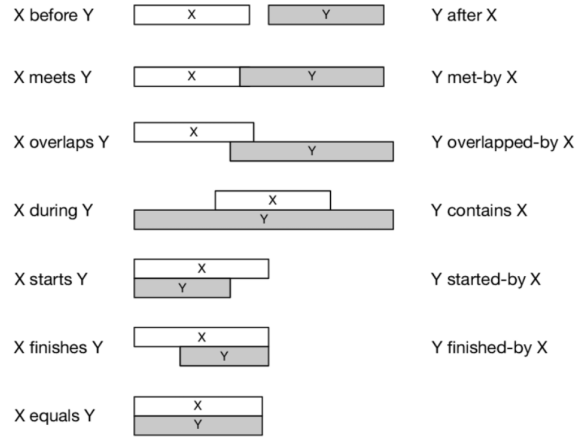


Figure 5.1: Visual representation of temporal operators